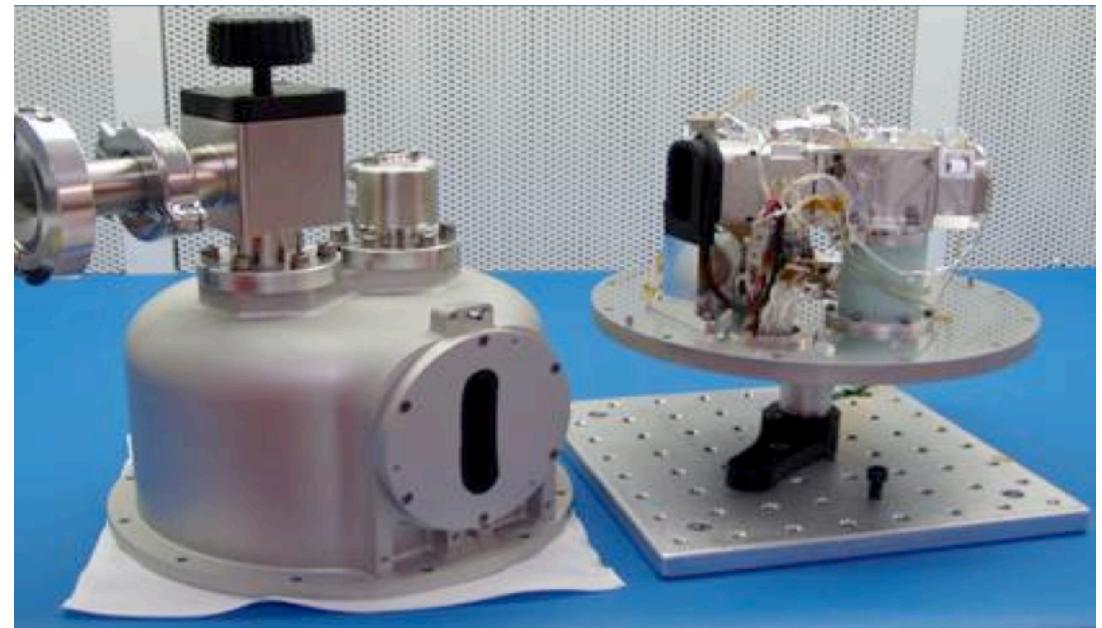




# Ultra Compact Imaging Spectrometer (UCIS)

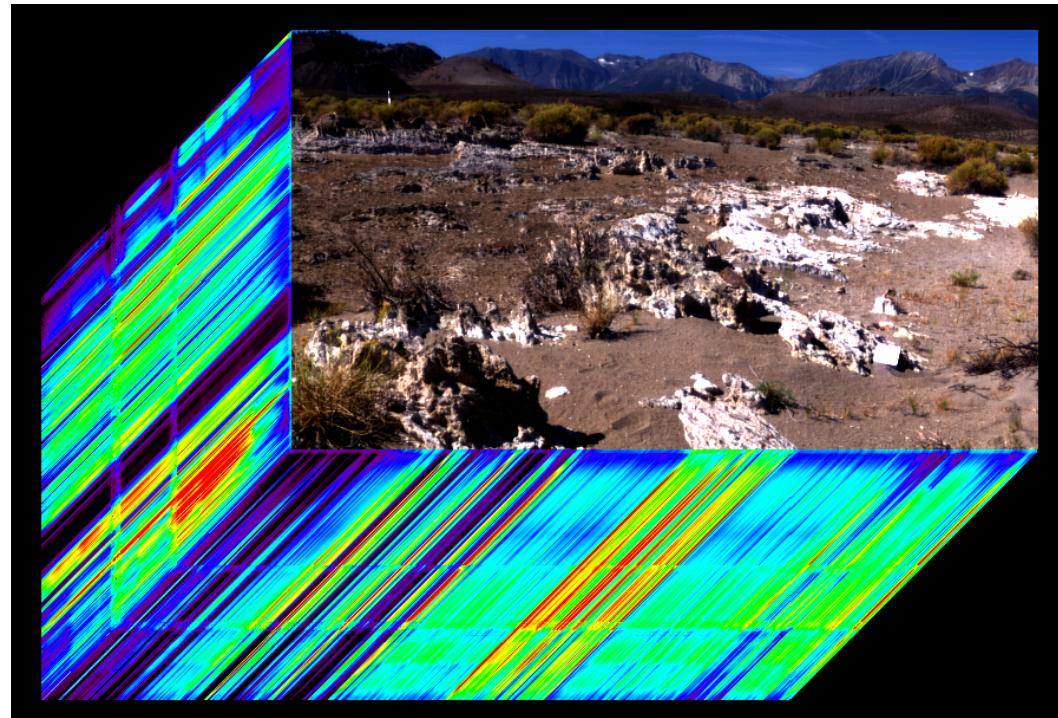
- Technical Challenges of In situ imaging spectroscopy
  - Limited mass, power, and data volume compared to orbiter/fly by spacecraft
- UCIS
  - Partnership between JPL (mast mounted sensor) and APL (electronics and software).
- Heritage
  - Sensor: JPL
  - Electronics/software: APL CRISM





# UCIS Approach: In situ imaging spectroscopy

- UCIS uses in situ imaging spectroscopy from 500->2600 nm to determine the mineralogy and composition of planetary surfaces and map their spatial relationships.
- Established technique with well developed mineral libraries and theoretical basis.
  - Used on most bodies in the solar system from orbit/flybys: Links compositions seen from orbit/flyby to in situ with same technique.
- Well understood measurement requirements.





# Key Instrument Characteristics

## Spectrometer Characteristics

Spectral	Range	500–2600 nm
	Sampling	10 nm
Spatial	Field of view	30 deg
	Instantaneous FOV	1.4 mrad
	Spatial swath	380 pixels
Radiometric	Range	0–100% R
	SNR	>300 *
Uniformity	Spectral cross-track	>97% **
	Spectral IFOV mixing	<3% ***

\*Specified through entire spectral range, for typical hematite reflectance; \*\*straightness of monochromatic slit image (smile <3% of pixel width); \*\*\* misregistration of spectrum to array row (keystone)





# USIS at Start of MatISSE

Mast Mounted Head		Electronics in Rover		
Calibration		On Board Data Management	Green indicates elements with sufficient maturity for flight (TRL6).	
Telescope/ Spectrometer/ Focal Plane		Focal Plane Electronics	Yellow identifies elements proposed for maturation under MatISSE.	
Telescope/Spectrometer		Calibration Motor Electronics	Optical hardware is on the mast, while the electronics are located in the rover/lander body.	
Grating		Thermal Electric Cooler Electronics	All Components are currently TRL 6 or higher.	
Slit			MatISSE improving subsystem TRL and instrument TRL.	
Thermal Design				
Pulse Tube Micro-cooler				
Environments				
Mars				
Moon				



# MATISSE Objectives

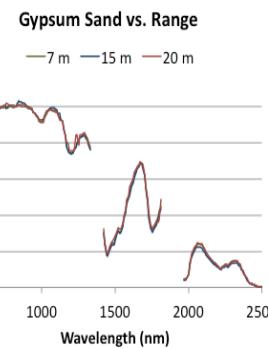
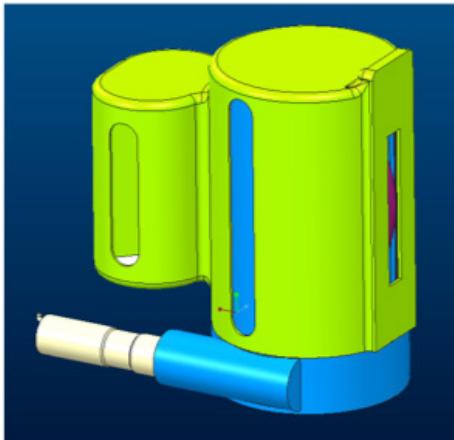
Develop and test to TRL 6:

- Thermal design for Mars and Moon (including pulse tube micro-cooler) and Calibration front end.
- Fully integrate mast unit using existing spectrometer, new thermal design (including micro-cooler) and calibration front end on spectrometer

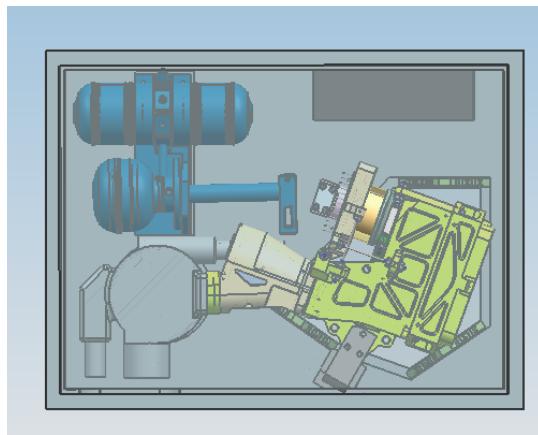
Develop data processing algorithms and test using UCIS measurements. Generate an overall design that can be implemented with flight-qualified parts.



# Results of Year 1

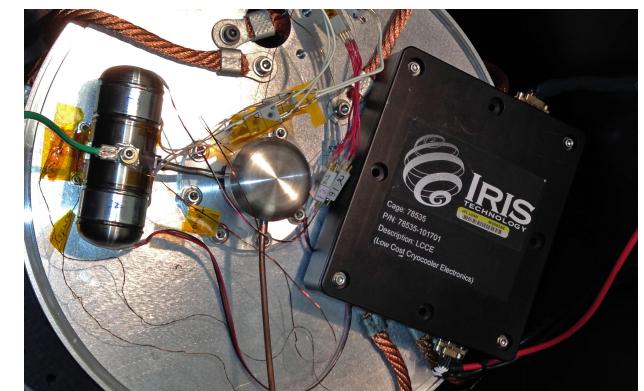


Calibration  
Assembly  
Designed and  
Validated



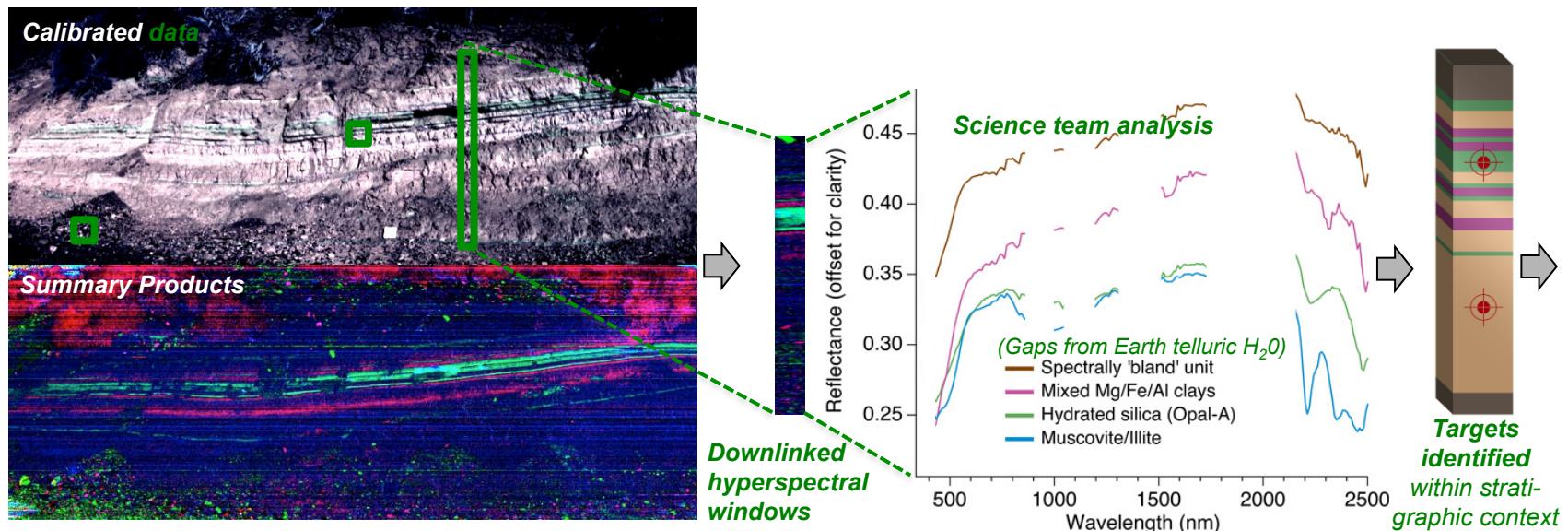
Integrated mechanical /  
thermal design.

Micro-coolers and  
electronics  
tested together. Micro-  
cooler now at TRL 6





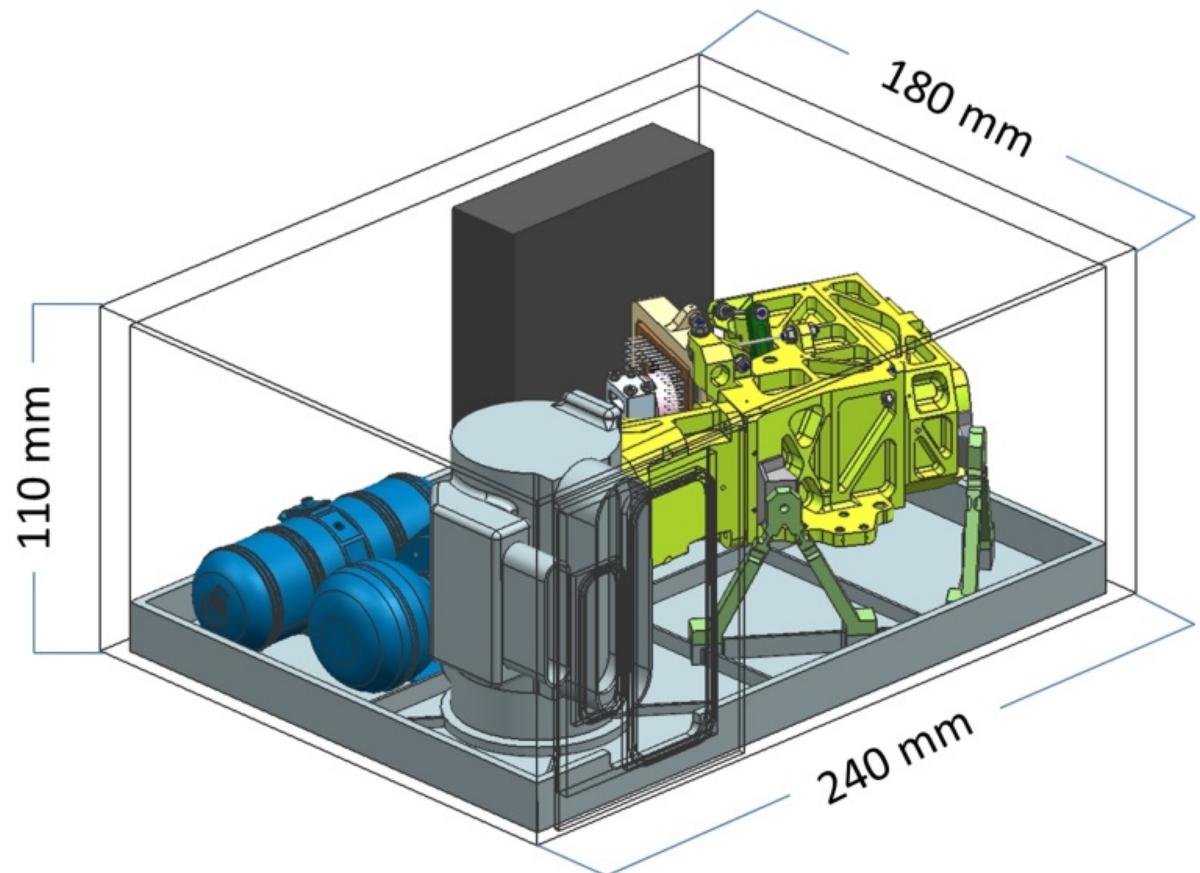
# Data Processing Example: Mills Creek, Mono-Lake, CA





# Possible Flight Configuration

Variable	CBE Value
Sensor Head Mass	2.6 kg
DPU Mass	1.2 kg
Sensor Volume	4752 cm <sup>3</sup>
DPU Volume (L1)	1345 cm <sup>3</sup>
Power (peak)	32 W
Power (average)	28 W





# Year 2 and 3

- Year 2:
  - Build Calibration Assembly Qualification Model
    - Test in appropriate
  - Get flight-like micro-cooler, validate thermal design, test micro-cooler.
- Year 3
  - Build flight-like sensor head (includes spectrometer, micro-cooler, and calibration assembly).
  - Test in Martian and Lunar Environments.



## For Additional Information

- Please contact:

Diana Blaney

[Diana.L.Blaney@jpl.nasa.gov](mailto:Diana.L.Blaney@jpl.nasa.gov)

818-354-5419

4800 Oak Grove Drive

MS 264-528

Pasadena, CA 91001